

Challenges in Control

A tribute to LIDS and Sanjoy

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Lund Univers

Proceedings **IBM Scientific Computing Symposium** Control Theory and Applications

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SESSION 1

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SESSION II

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SESSION III

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Symposium Technical Plan

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EATON, J. H., Manager, Cont IBM Corporation, San Jose,

GAZIS, D. C., Thomas J. Wat IBM Corporation, Yorktown









SESSION I: Theory and Computations I

- **Optimal Programming and Control**
- Toward a Theory of Difficulty of 2 Computation in Optimal Control
- Some Aspects of the Relationship of 3 Dynamic Programming to the Calculus of Variations

SESSION II: Theory and Computations II

- On Certain Differential Games
- Applications of Liapunov Stability Theory 5 to Control Systems
- Stability of the Optimal Control Problem 6

SESSION III: Industrial Processes

- Application of Optimal Methods to Control 7 of Industrial Processes
- Control Theory and Applications in 8 Chemical Process Control
- .9 Control Problems in Papermaking

SESSION IV: Special Processes

- Control Problems in Automobile Traffic 10
- Application of Control Theory to 11 **Biological Systems**
- Minimum-Fuel Impulses for Space 12 Trajectories

SESSION V: Mathematical Techniques and Methods

- Discontinuous Variational Problems 13
- **Optimal Control and Convex Program** 14
- 15 Stochastic Problems in Control



- -ARTHUR E. BRYSON, JR.
 - -R. E. KALMAN

-STUART E. DREYFUS

- -L. S. PONTRYAGE
- -J. P. LASALLE -LAWRENCE MARKUS





-THEODORE J. WILLIAMS

-K. J. ASTROM 185

- -DENOS C. GAZIS
- -FRED S. GRODINS
- -LUCIEN W. NEUSTADT



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ming	-J. B. ROSEN	223	TY W
	-W. M. WONHAM	239	MR.







A Perspective

Emergence

Drivers: World War II Formation of the field The Servomechanisms Laboratory 1940

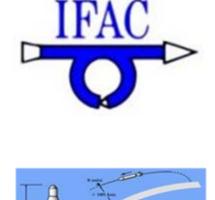
The Second Phase

Drivers: Space race, computer control Subspecialization: ...

The Third Phase?

Drivers: Complex networked systems, Safe embedded systems Autonomy Recover the holistic view









Control Everywhere





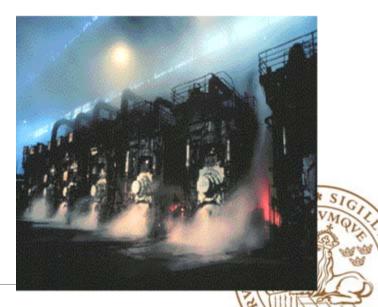












The Power of Feedback

- Accurate systems from imprecise components
- Reduce effects of disturbances and component variations
- Regulate, stabilize, and shape behavior
- Drawbacks:

Risk of Instability

Sensor noise is fed into the system



A Third Phase?

- Drivers: embedded systems, networks, biology, physics, economy ...
- > Autonomous distributed systems
- Sensor and actuator rich systems
- Provable safe design and reconfiguration
- Can the holistic view be recovered?



Physics

Nobel Prizes

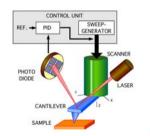
Dahlén 1912

van der Meer 1984

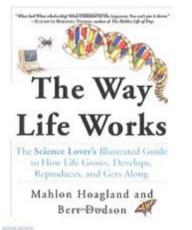
- Instruments mega to nano
- > Turbulence
- Quantum and molecular systems



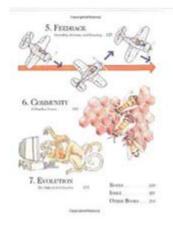






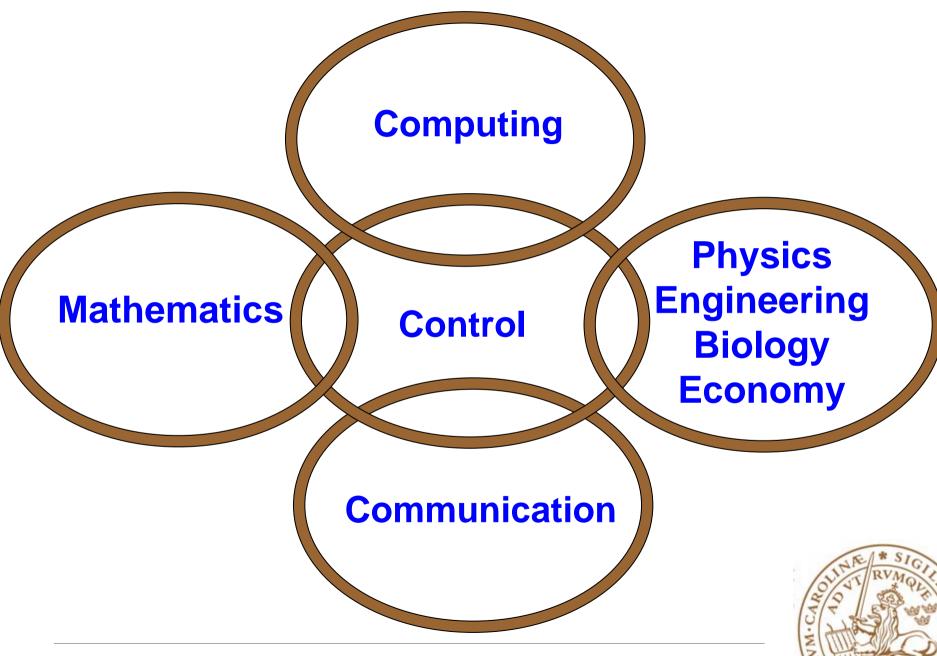




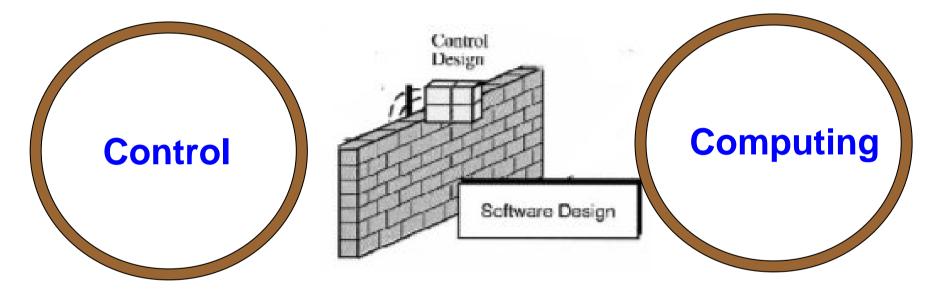


Feedback is a central feature of life. The process of feedback governs how we grow, respond to stress and challenge, and regulate factors such as body temperature, blood pressure, and cholesterol level. The mechanisms operate at every level, from the interaction of proteins in cells to the interaction of organisms in complex ecologies.

Mahlon B Hoagland and B Dodson The Way Life Works Times Books 1995



The CS Barrier

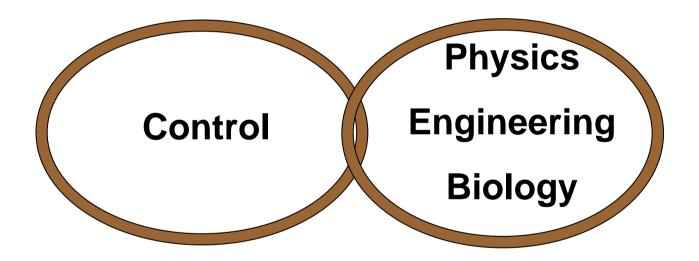


Feedback,Stability, ODE, PDE Moderate complexity Robustness Logic, languages, DES,FSM High complexity, abstractions

Architecture

The controller

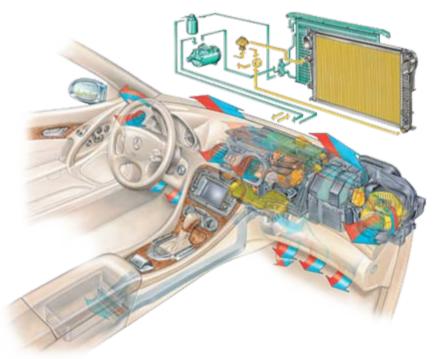
The Physics Barrier



Blockdiagrams ODEs Mass, energy, momentum

Block diagrams unsuitable for serious physical modeling

Automotive Climate Control



Audi, BMW, DaimlerCrysler, Volkswagen and their suppliers have standardized on Modelica

Suppliers provide components and validated Modelica models based on the AirConditioning library from Modelon

Car manufacturers evaluate complete system by simulation

> IP protected by extensive encryption



Picture courtesy of Behr GmbH & Co.

Summary

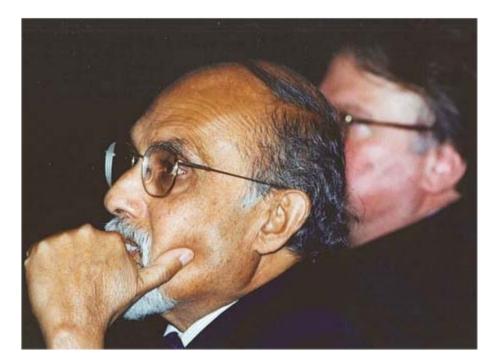
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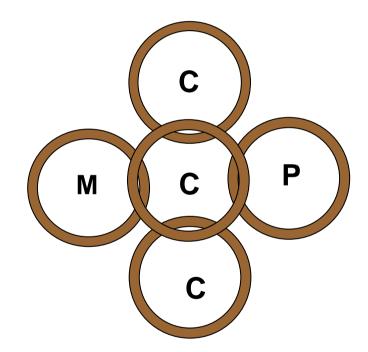
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- Control is a vital dynamic field
- Networked embedded systems c
- Autonomy and safety
- The educational challenge
- Recover the holistic view



Sanjoy's Half Plane





Thanks for all your contributions! Continue to deepen insight and understanding !