Paths Ahead in the Science of Information and Decision Systems

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- data sets: n samples in p dimensions
 - \blacktriangleright computational biology: p genes measured in n humans
 - computer vision: p textures or objects, n images
 - \blacktriangleright natural language processing: p word frequencies over n documents
 - financial engineering: p stocks sampled at n distinct times
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- blessings of dimensionality:
 - $\begin{tabular}{c} \hline concentration of measure: \\ \hline predictable \end{tabular} high-dimensional quantities can be remarkably \\ \hline \hline predictable \end{tabular} \end{tabular} \end{tabular}$
 - <u>hidden "effective" dimensionalities</u>: sparsity in vectors/matrices; eigen-decay in matrices/operators; Markov relations, latent variables etc.

Example: Eigenanalysis in high-dimensions

Set-up: Collect *n* samples $\{Y_i\}_{i=1}^n$ of zero-mean random vector with covariance $\Sigma \in \mathbb{R}^{p \times p}$.

Goal: Estimate eigenstructure (eigenvalues and vectors) of Σ , say using the sample covariance $\widehat{\Sigma}_n = \frac{1}{n} \sum_{i=1}^n Y_i Y_i^T$. Look at scaling as $(n, p) \to +\infty$.

Uses/relevance: Principal components analysis, canonical correlation analysis, spectral clustering etc. ...

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Eigenspectrum concentrates on interval $\left[\left(1-\sqrt{\frac{p}{n}}\right)^2, \left(1+\sqrt{\frac{p}{n}}\right)^2\right]$.

(e.g., Marcenko & Pastur, 1967, Geman, 1980, Szarek, 1991)

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Eigenanalysis with structural constraints:

- Some models:
 - ▶ Spiked covariance models with sparse eigenvectors
 - ▶ Covariance matrices with rapid eigendecay
 - ▶ Inverse covariance matrices with Markov structure (i.e., Gaussian graphical models)

2 Some estimators:

- ▶ thresholded versions of sample covariance
- ▶ regularized *M*-estimators (based on solving convex programs)

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▶ Pairwise MRF (Ising model, 1923)

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▶ Triplet MRF

$$\mathbb{P}(x_1,\ldots,x_p) = \frac{1}{Z(\theta)} \exp\big\{\sum_{s\in V} \theta_s x_s + \sum_{(s,t)\in E_2} \theta_{st} x_s x_t + \sum_{(s,t,u)\in E_3} \theta_{stu} x_s x_t x_u\big\}.$$

• (hyper)graph structure enforces that $\theta_{uv} = 0$ for all $(uv) \notin E$

Example: Learning social network structure



Graphical model fit to voting records of US senators (using technique from Ravikumar et al., 2008)

Empirical behavior: Unrescaled plots



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Empirical behavior: Appropriately rescaled



$\S 2.$ Trade-offs between computation and statistics

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- some open questions:
 - for fixed sample size n, when does more computation guarantee greater accuracy?
 - ► can we derive fundamental limits that include upper bounds on computation?
 - \blacktriangleright does computational complexity versus sample size n exhibit non-monotonic behavior?

Empirical performance of thresholding



- spiked covariance model $\Sigma = zz^T + \sigma^2 I$
- model selection: find k-sized subset $S \subset \{1, \ldots, p\}$ where $z \in \mathbb{R}^p$ is non-zero
- plot the success probability $\mathbb{P}[\widehat{S} = S^*]$ versus sample size n.

Empirical performance of thresholding



• success prob. versus rescaled sample size:

$$\theta_{\rm thr}(n,p,k) = \frac{n}{k^2 \log(p-k)}$$

More computationally expensive SDP relaxation



Summary

- contributions possible/required from multiple disciplines:
 - electrical engineering
 - ► computer science
 - statistics
 - applied mathematics
- optimization theory and statistics:
 - ▶ need theory for analyzing random ensembles of optimization problems
 - need algorithms for solving large-scale instances
- control theory and statistics:
 - ▶ on-line learning introduces interesting dynamical aspects
 - stochastic approximation
- information-theoretic methods in learning:
 - ▶ statistical inference \equiv (non-orthodox) communication channel:
 - ★ codewords/codebook ≡ parameter θ in set Θ
 - ★ drawing samples \equiv using channel
 - ▶ fundamental lower bounds via Fano and other methods
- applied probability and statistics:
 - ► large deviations; concentration of measure
 - empirical process theory

Traditional asymptotics



Challenge: High-dimensional scaling laws



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Example: (Sparse) linear regression



Set-up: • vector $\beta^* \in \mathbb{R}^p$ with at most $k \ll p$ non-zero entries

• noisy observations
$$y = X\beta^* + w$$

Goal: Generate "good" estimate $\hat{\beta}$ of β^* (various loss functions: prediction, ℓ_2 -loss, model selection)

Applications: Imaging; data-base sketching; compressed sensing.

Some relevant work: Portnoy, 1984; Tibshirani, 1996; Chen et al., 1998; Donoho/Xuo, 2001; Tropp, 2004; Fuchs, 2004; Meinshausen/Buhlmann, 2005; Candes/Tao, 2005; Donoho, 2005; Haupt & Nowak, 2006; Zhao/Yu, 2006; Wainwright, 2006; Tsybakov et al., 2008

Example: Structured matrix estimation



Set-up: Samples from random vector with structured covariance Σ , or structured inverse covariance Θ .

Goal: Produce estimates $\hat{\Sigma}$ (or $\hat{\Theta}$) close in Frobenius or spectral norm.

Applications: Social network analysis, computer vision, financial time series analysis, geostatistics....

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